

Chaos in Many-Particle Systems

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Molecular Dynamics: Definition

“...molecular dynamics simulation involves solving the classical many-body problem in contexts relevant to the study of matter at the atomistic level...”¹

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²M. P. Allen and D. J. Tildesley, *Computer Simulation of Liquids*.

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“...molecular dynamics simulation involves solving the classical many-body problem in contexts relevant to the study of matter at the atomistic level...”¹

“Computer simulation generates information at the microscopic level ... and the conversion of this very detailed information into macroscopic terms ... is the province of statistical mechanics.”²

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Interaction Potentials

- The Lennard-Jones potential is defined by

$$u(r_{j,k}) = \begin{cases} 4\varepsilon \left[\left(\frac{\sigma}{r_{j,k}} \right)^{12} - \left(\frac{\sigma}{r_{j,k}} \right)^6 \right], & \text{for } r_{j,k} < r_c, \\ 0, & \text{for } r_{j,k} \geq r_c, \end{cases} \quad (1)$$

where $r_{j,k} = |\vec{r}_j - \vec{r}_k|$, ε is the interaction magnitude, and σ defines a length scale.

- By removing the attractive part of the Lennard-Jones potential, we obtain the soft-sphere potential:

$$u(r_{j,k}) = \begin{cases} 4\varepsilon \left[\left(\frac{\sigma}{r_{j,k}} \right)^{12} - \left(\frac{\sigma}{r_{j,k}} \right)^6 \right] + \varepsilon, & \text{for } r_{j,k} < r_c, \\ 0, & \text{for } r_{j,k} \geq r_c, \end{cases} \quad (2)$$

for $r_c = 2^{\frac{1}{6}}\sigma$.

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Potential Sketch

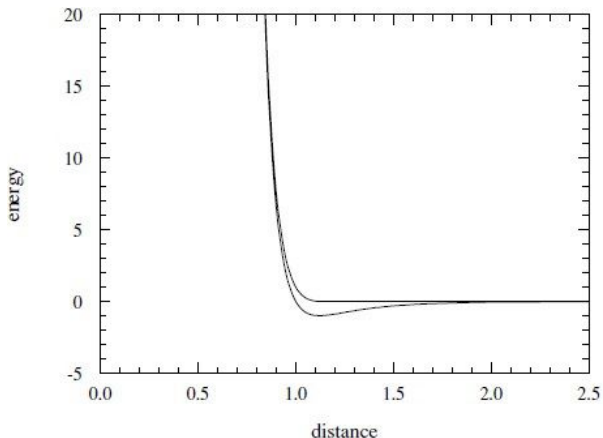


Figure 1: Lennard-Jones (lower curve) and soft-sphere (upper curve) potentials in dimensionless molecular dynamics units.¹

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Perturbation

- Consider two identical simulations of N two-dimensional particles. At a chosen time t_p , the following perturbation is applied on every particle in one of the systems:

$$\vec{v}_{2,j}(t_p) = \vec{v}_{1,j}(t_p) + \varepsilon \vec{w}_j, \quad (3)$$

where $\vec{v}_{1,j}$ is the velocity of the j -th particle in the original system, $\vec{v}_{2,j}$ is the corresponding velocity in the perturbed system, \vec{w}_j is a random unit vector, and ε is the perturbative parameter.

Criteria for Chaos

- Mean-square position deviation:

$$\langle (\vec{r}_1 - \vec{r}_2)^2 \rangle = \frac{1}{N} \sum_{j=1}^N (\vec{r}_{1,j} - \vec{r}_{2,j})^2, \quad (4)$$

where $\vec{r}_{1,j}$ is the position of the j -th particle in the original system and $\vec{r}_{2,j}$ is the corresponding position in the perturbed system.

- Position correlation:

$$\text{corr}(\vec{r}_1, \vec{r}_2) = \frac{\langle (\vec{r}_1 - \langle \vec{r}_1 \rangle)(\vec{r}_2 - \langle \vec{r}_2 \rangle) \rangle}{\sigma(\vec{r}_1)\sigma(\vec{r}_2)}, \quad (5)$$

where $\sigma(\vec{r}_j) = \sqrt{\langle (\vec{r}_j - \langle \vec{r}_j \rangle)^2 \rangle}$.

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Comparative Simulation

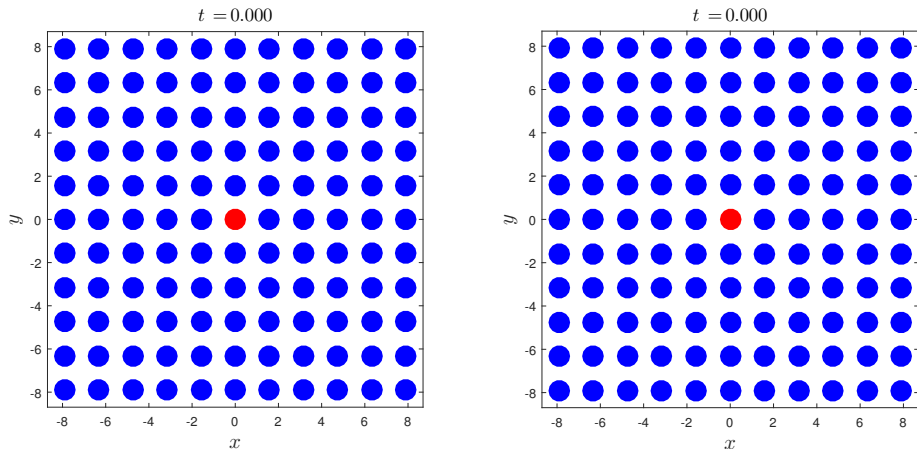


Figure 2: Comparative simulation of two-dimensional soft-sphere particles for $\rho = 0.4$, $T = 1$, $N = 121$, and $\varepsilon = 10^{-6}$.

Root-Mean-Square Position Deviation and Correlation

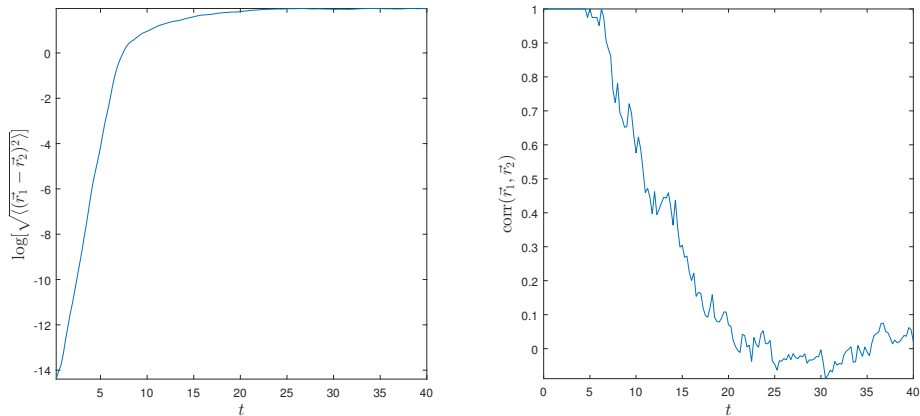


Figure 3: Root-mean-square deviation (left panel) and correlation (right panel) between particle positions and their perturbed versions. Simulation of soft-sphere particles for $d = 2$, $\rho = 0.4$, $T = 1$, and $N = 121$.

Saturation

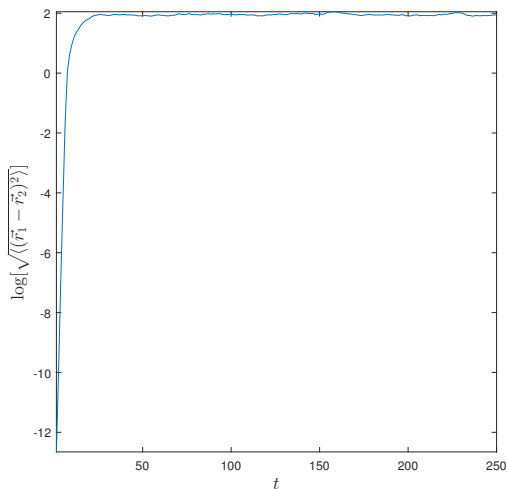


Figure 4: Root-mean-square deviation between particle positions and their perturbed versions. Simulation of soft-sphere particles for $d = 2$, $\rho = 0.4$, $T = 1$, and $N = 121$.

Saturation Value

- According to figure 4, the saturation value of the root-mean-square position deviation is

$$\log \left[\sqrt{\langle (\vec{r}_1 - \vec{r}_2)^2 \rangle} \right] \approx 1.947, \quad (6)$$

for $t = 250$.

- As a consequence of the derivation presented in the appendix, the predicted value of saturation is

$$\log \left[\sqrt{\langle (\vec{r}_1 - \vec{r}_2)^2 \rangle} \right] = \log \left(\sqrt{\frac{d}{12}} L \right) \approx 1.960, \quad (7)$$

for $d = 2$ and $L \approx 17.39$.

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Maxwell-Boltzmann Distribution

- Velocity distribution of two-dimensional classical particles in thermal equilibrium:

$$f(\mathbf{v}) = \frac{v}{T} \exp\left(-\frac{v^2}{2T}\right). \quad (8)$$

- The Boltzmann H -function is defined as

$$\begin{aligned} H &= \int \tilde{f}(\vec{v}) \log [\tilde{f}(\vec{v})] d^d v \\ &\propto \int f(\mathbf{v}) \log \left[\frac{f(\mathbf{v})}{v^{d-1}} \right] d\mathbf{v}. \end{aligned} \quad (9)$$

- The H -function satisfies the following relation:

$$\left\langle \frac{dH}{dt} \right\rangle \leq 0, \quad (10)$$

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H-Function

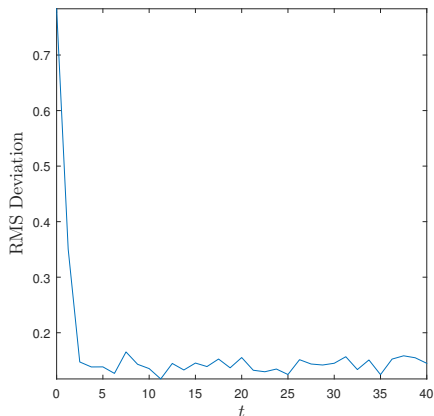
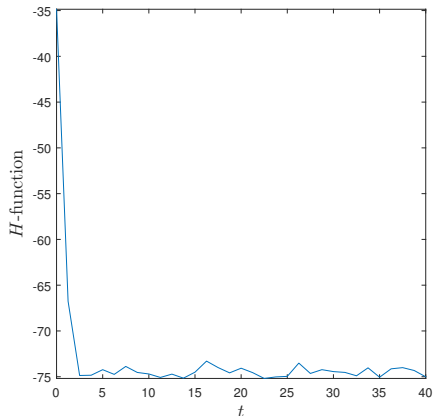


Figure 5: (Left panel) Boltzmann H -function. (Right panel) Root-mean-square deviation of the velocity histogram with respect to the Maxwell-Boltzmann distribution. Simulation of soft-sphere particles for $d = 2$, $\rho = 0.4$, $T = 1$, and $N = 121$.

Thermalized Comparative Simulation

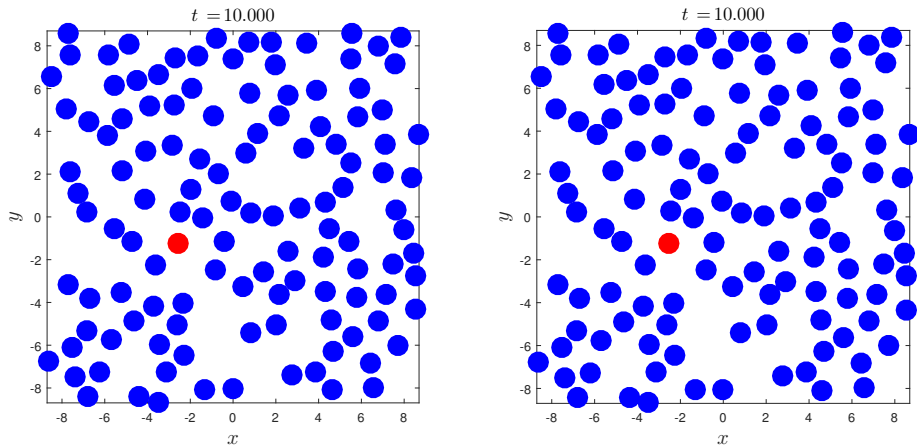


Figure 6: Comparative simulation of thermalized two-dimensional soft-sphere particles for $\rho = 0.4$, $T = 1$, $N = 121$, and $\varepsilon = 10^{-6}$.

Position Root-Mean-Square Deviation and Correlation

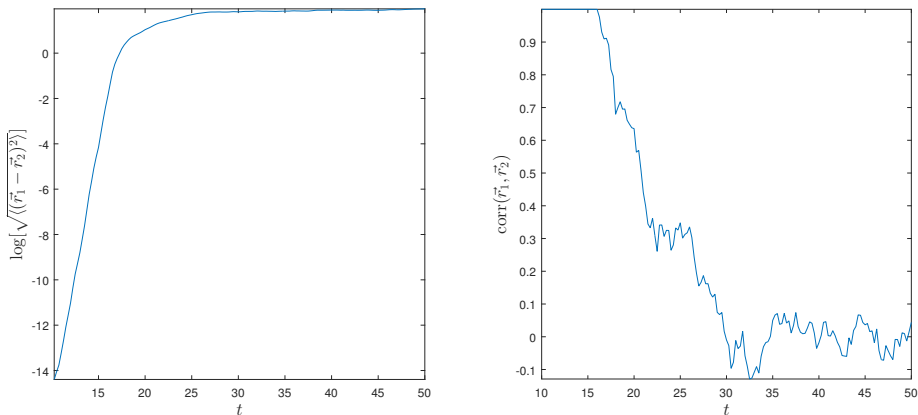


Figure 7: Root-mean-square deviation (left panel) and correlation (right panel) between particle positions and their perturbed versions. Simulation of thermalized soft-sphere particles for $d = 2$, $\rho = 0.4$, $T = 1$, and $N = 121$.

Behaviour Invariance

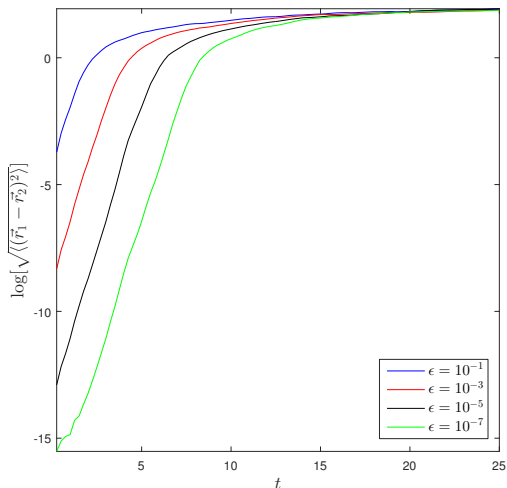


Figure 8: Root-mean-square deviation between particle positions and their perturbed versions. Simulation of soft-sphere particles for $\rho = 0.4$, $T = 1$, and $N = 121$.

References

- D. C. Rapaport. *The Art of Molecular Dynamics Simulation*. Cambridge University Press, 2004.

Saturation Value of Mean-Square Position Deviation

- As a first step, equation (4) is rewritten in terms of Cartesian coordinates:

$$\begin{aligned} \langle (\vec{r}_1 - \vec{r}_2)^2 \rangle &= \sum_{j=1}^d \langle (r_{1,j} - r_{2,j})^2 \rangle \\ &= \sum_{j=1}^d \langle (\Delta r_j)^2 \rangle, \end{aligned} \tag{11}$$

where $r_{1,j}$ and $r_{2,j}$ are the j -th Cartesian coordinates of a particle in the original and perturbed systems, respectively. Notice that d dimensions are considered.

- Assuming that Δr_j is a uniformly distributed random variable over the interval $[0, L_j/2]$, the following result is obtained:

$$\langle (\Delta r_j)^2 \rangle = \frac{1}{12} L_j^2, \tag{12}$$

where L_j is the length of a d -dimensional box in the j -th direction, considering periodic boundary conditions.

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Result

- Upon substitution of the assumption (12) into equation (11):

$$\langle (\vec{r}_1 - \vec{r}_2)^2 \rangle = \frac{1}{12} \sum_{j=1}^d L_j^2. \quad (13)$$

- In the case of $L_j = L$, for all j , equation (13) is simplified:

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