



# PGF 5005 - Mecânica Clássica

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## Respostas - Primeira Lista de Exercícios

1.

(a)

$$L = \frac{m}{2}[(v_0 + at)(v_0 + at + 2l\dot{\theta} \cos \theta) + l^2\dot{\theta}^2] + mgl \cos \theta$$
$$H = \frac{p^2}{2ml} + (v_0 + at) \left[ \frac{m}{2} ((v_0 + at) \cos^2 \theta - 1) - \frac{p}{l} \cos \theta \right] - mgl \cos \theta$$

(b)

$$\ddot{\theta} + \frac{g}{l} \sin \theta + \frac{a}{l} \cos \theta = 0$$

(c)

$$\theta_e = \tan^{-1} \left( -\frac{a}{g} \right)$$

(e)

$$\ddot{\theta} + \frac{(g+a)}{l} \sin \theta = 0$$

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3.

(a)

$$L = \frac{m\dot{q}^2}{2} - \frac{\omega^2 q^2}{2} + \frac{Aq^3}{3}$$
$$H = \frac{p^2}{2m} + \frac{\omega^2 q^2}{2} - \frac{Aq^3}{3}$$

(b)

$$\frac{dH}{dt} = 0$$

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4.

(a)

$$\{Q, P\} = 1 \Rightarrow \alpha = \frac{1}{2}, \beta = 2$$

(b)

$$F_3 = -\frac{Q^2 \tan(2p)}{2}$$

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5.

Usando uma função geratriz do tipo,

$$F(q_1, p_2, P_1, P_2) = F_1 + q_2 p_2 - Q_1 P_1 - Q_2 P_2$$

encontra-se

$$F = q_1(P_1 + 2p_2) + P_2 p_2$$

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8.

(b)

$$I = \frac{2a\sqrt{2mE}}{\pi}, \quad \theta = \begin{cases} -\frac{\pi}{2} + \frac{\pi^2 I}{4ma^2} t, & 2nT < t < (2n+1)T \\ \frac{\pi}{2} - \frac{\pi^2 I}{4ma^2} t, & (2n+1)T < t < (2n+2)T \end{cases} \quad \text{onde } T = 2a/v_0 \text{ e } n = 0, 1, \dots$$

(d)

$$H = \frac{p^2}{2m}, \quad H = \frac{\pi^2 I^2}{8ma^2}$$

(e)

$$x = \frac{2a}{\pi}\theta, \quad p = \begin{cases} \frac{\pi}{2a}I, & 2nT < t < (2n+1)T \\ -\frac{\pi}{2a}I, & (2n+1)T < t < (2n+2)T \end{cases} \quad \text{onde } T = 2a/v_0 \text{ e } n = 0, 1, \dots$$

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11.

(a)

$$\theta_1(t) = \theta_1^0 + (1 - 2I_1^0 - 3I_2^0)t, \quad \theta_2(t) = \theta_2^0 + (1 - 3I_1^0 + 2I_2^0)t$$